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#### **MAGSWITCH ELAY30x5**

P/N: 81401338 + 1(303) 468.0662 magswitch.com

## ELAY30x5 Smart Tool | P/N: 81401338

Featuring Variable Field Output (VFO) technology, this heavy lifter designed for crane use can be controlled using CANopen protocols to de-stack and pick single or multiple sheets. Adjustability of magnetic strength between 0 and 100% allows use of this magnet on parts of varying sizes and material type. CANopen communication allows integration of multiple tools on the same CANopen bus, controlled simultaneously.

NOTE: Base tool does not ship with 88001111 EOAT bracket (transparent at right)

## **Specifications**

Maximum Breakaway Force 1,2	2186.9 N
Thickness for De-Stack <sup>3</sup>	0.016" / 0.4mm
Nominal Supply Voltage	24 V DC
Peak Power Draw	2.5 A DC @ 24 V DC
Net Weight	12.6 lb / 5.7 kg
Connector Type	Male M12x1.0 – 5 Pin – A-coded
Mounting Options	6-M6-M6-6 (Both Sides)
Magnetic Pole Footprint	7.33" x 1.6" / 186.2 x 41 mm



Material Thickness	0.6	1.0	1.5	2.0	3.0	4.0	5.0	6.0	7.0	9.5	50.0
- mm (in)	(.024)	(.039)	(.059)	(.079)	(.118)	(.157)	(.197)	(.236)	(.276)	(.374)	(1.97)
Maximum Force 1,2,4,5 - Newtons (N)	263.8	536.4	654.1	862.0	1016.0	1274.9	1646.5	1803.4	2002.5	2185.9	2186.9

$$SWL (Safe Working Load) = \frac{Maximum Force^5}{Safety Factor (\geq 3)}$$

- <sup>1</sup> Determined in laboratory environment on SAE1018 Steel with surface roughness 63 micro inches with optimized pole shoes. Many factors contribute to the actual breakaway force and safe working load in each application. Consult a Magswitch Applications Engineer and test the Magswitch in each application before deployment.
- <sup>2</sup> All data applies to unit with standard pole shoes installed.
- <sup>3</sup> Determined with SAE1018 Steel L=200mm W=200mm.
- $^{4}$  Values may vary by  $\pm$ /- 5%.
- <sup>5</sup> Maximum forces listed above are not safe lifting forces. Designer must take into account safety factor when specifying tool. Magswitch recommends SWL = 3:1 for most lifting applications.



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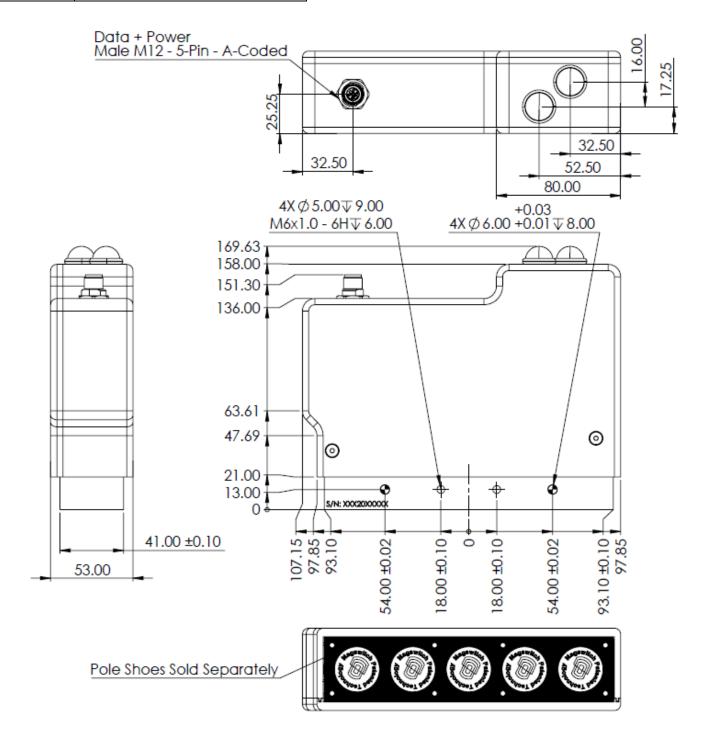
### Pole shoes required for operation

#### **Standard Kits Available:**

	ELAY30x5 Standard Pole Shoe Kit
8800968	ELAY30x5 Thin Target Pole Shoe Kit
88001111	ELAY30x5 Standard EOAT Bracket

### **WARNING!**

Do Not Operate Unless In Contact With Ferrous Target!





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## **General Electrical Characteristics**

Parameter	Value
Input Voltage Range	24 ± 5% V DC
Inrush Current (70 ms duration)	3 A Max
Rated Current Draw (Peak)	2.5 A DC @ 24 V DC
Rated Current Draw (Continuous)	1 A DC @ 24 V DC
Connector on Tool	Male M12 – 5 Pin – A-Coded

## **Ambient Conditions**

Parameter	Range
Ambient Temperature (Operation)	-10 to +40 Degrees Celsius
Ambient Temperature (Storage)	-25 to +80 Degrees Celsius
Relative Humidity (non-condensing)	0 to 95%

## **LED Color Codes**

Function/State	Blue LED State	Green LED State
No power to tool	OFF	OFF
Waiting to home magnet	Blinking	Blinking
Magnet actuated OFF	ON	OFF
Magnet actuated ON 100% (Fail-Safe)	ON	ON
Magnet partially actuated	ON	Blinking
Standard calibration routine	Blinks when calibration mode is entered	OFF/ON depending on magnet state
	Blinks when steps 1-4 are confirmed	
Auto-calibration routine	Blinks on entry and exit/confirmation	OFF/ON depending on magnet state

## **Connector Pinout**

Pin #	Function	Logic
1	Signal Shield	-
2	Vin (V+)	+24 VDC
3	GND (V-)	GND
4	CANopen bus high	TX/RX high line (D1) (CAN H)
5	CANopen bus low	TX/RX low line (D0) (CAN L)



Cable Side: Pin Assignment M12, 5-pin, A-coded, Female Connector (socket-side) View



Tool side: Pin Assignment M12, 5-pin, Acoded, Male Connector (pin-side) View

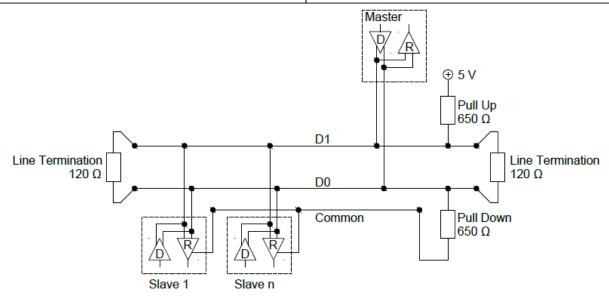
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## **CANopen Configuration Information**

CAN Baud Rate	250 kBaud, configurable
Default CAN Node ID	127 <sub>d =</sub> 7F <sub>h</sub> , configurable
Device Terminating Resistor	120 Ω <b>NOT</b> enabled
Device Terminating mesistor	Bus must have 120 $\Omega$ termination resistor installed
	Master device must have line polarization/termination <b>OR</b> :
Master Device Termination	Apply 450-650 $\Omega$ pull-up to $+5V$ on high line (D1) (CAN_H)
	Apply 450-650 $\Omega$ pull-down to GND on low line (D0) (CAN_L)



### **Changing CANopen NodelD**

- Check object 2009<sub>h</sub> for current CANopen NodelD.
  - a. Default NodelD =  $127_d = 7F_h$
- 2. Write desired NodelD value to 2009h.
  - a. Acceptable NodelD value range = 1<sub>d</sub>-127<sub>d</sub>
- To save, write to object 1010<sub>h</sub> sub-index 02<sub>h</sub> the value 1702257011<sub>d</sub> (65766173<sub>h</sub>).
- 4. Wait until object 1010<sub>h</sub> sub-index 02<sub>h</sub> is equal to 1.
- 5. Disconnect and reconnect power.
- 6. The device NodelD will now be changed.

#### **Changing CANopen Baud Rate**

Please consult integration/assembly manual 1101334 for instructions on changing the CANopen baud rate. Available baud rates are 10, 20, 50, 125, 250, 500, and 1000 kBaud.

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### **CANopen I/O Service Data Objects (SDO's) and Functionality**

Туре	Object (hex)	Sub Index (hex)	Short Name	Description
				1 = home magnet
	2400	01	Move Enable	2 = move to position set in 2400:02
				0 = reset trigger after each move
	2400	02	Set Position	Position 0-100% (increments of 1)
				Standard Calibration: 1 = trigger (must be reset to 0 after each
			0.111	trigger in standard calibration)
S	2400	03	Calibration Trigger	Auto Calibration: 1 = start (with Calibration Mode already set to 1)
Inputs				999 = exit & don't save
=	2400	04	Calibration Select	0 = reset trigger after setting 1 or 999
	2400	04	Campration Select	Select calibration storage options 0-3 (4 possible calibrations)  default = 0
				more sensitive = -x
	2400	05	Sensitivity	less sensitive = x
				typical x values = 5, 10, 20
				0 = standard calibration procedure (good for bin picking, etc)
	2400	06	Calibration Mode	1 = auto calibrate
	2500	01	Magnet Position	0-100% (<=2 is considered 0)
	2300	01	Wagnet Fosition	0 = 0FF
	2500	02	Magnet State	1 = Partial ON
	2000		Wagnot otato	2 = Magnet ON 100% (Fail-Safe)
				0 = no South Pole, no North Pole, and no part present in range
				1 = only North pole on
	2500	03	Calibration State	2 = only South Pole on
				3 = both poles on, but no part present
				4 = North, South, part present all within Range
			In Calibration	0 = not in Calibration
	2500	04		1 = In Standard Calibration
				2 = In Auto Calibration
				0 = not in calibration
6		05	Calibration Step	1 = waiting for best circuit
Outputs	2500			2 = waiting for worst circuit
J				3 = waiting for South Pole
				4 = waiting for North pole
	2500	06	Cycle Count	Number of times the tool has been turned on to full power
	2500	07	Home Status	0 = not properly homed
				1 = Properly homed
	2500	08	Move Status	0 = not complete
	0500	00		1 = Last set move complete
	2500	09	Serial Number	Magswitch Tool Serial Number
	2500	0.4	Magnet Software	Magazinitah Saftuara Varsian
	2500	OA OB	Version Tool Type	Magswitch Software Version 30 for E30, 50 for E50
	2000	UD	Tourrype	$84_h = 132_d = 125$ kBaud by default.
	2005		CANopen Baud Rate	Consult configuration manual 1101334 before changing
				0-127 are permissible node IDs
	2009		CANopen Node ID	$7F_h = 127_d$ by default
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## 2-Step Calibration Procedure

See setup manual 1101334 for more E-series detail.

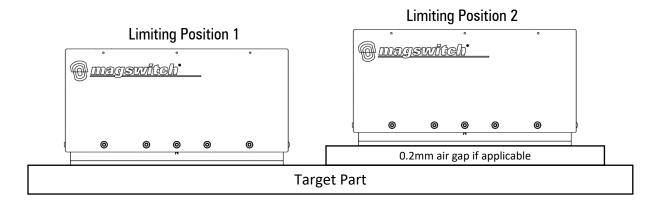
Step 1

Limiting Position 1 for Calibration Match Signal **Step 2** 

Limiting Position 2 for Calibration Match Signal

Object **CalState** (2500:03<sub>h</sub>) will return 4 when the contact quality between both poles and the part lie within the zone created by bounding Limiting Position 1, Limiting Position 2, and North and South Pole calibration signals.

NOTE: North and South pole calibration steps 3 and 4 typical of the E30 and E50 tools are removed from the ELAY calibration procedures. This is because the north and south poles of an ELAY tool are elongated, and in most customer applications it is difficult to position the long edge of the magnet near the edge of the part without also impacting the calibration of the opposite pole.



The following flowchart shows the proper CANopen signaling required to enter and set calibrations 0-4. Note that all "output" objects can be polled at any time to determine the current state of the calibration process.

It is critical that the magnet be fully actuated (setPosition / OutPos = 100) at each calibration step to guarantee proper field values are stored. The tool will not allow you to confirm calibration steps 1 and 2 unless the magnet is ON and the green light is lit.

The supplementary document 1101340 can be provided by Magswitch if additional information regarding calibration procedure is needed.

## **Auto-Calibration Procedure**

Actuate tool OFF and enter auto-calibration mode by setting object  $2400:04=1_d$  and then writing  $2400:03=1_d$ . Position the tool on the desired part. Once the tool is actuated ON and the green light is lit, the tool records magnetic field strengths in the current configuration and stores them as allowable Part Present boundaries. Add or adjust parts and fixtures to widen the allowable range of field strengths. By writing  $2400:03=0_d$ , auto-calibration parameters are saved and standard operation resumes. Tool should NOT be actuated OFF until auto-calibration is exited and saved otherwise calibration values will be skewed. Tool should not be actuated off-target or calibration range will exceed practical usage and part present functionality will be inaccurate.

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## **E-Series Operational Flowchart**

